

The Possible Role of Glial Cells in Processing Non-Automatic Responses

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Abstract

Taking inspiration from recent findings about properties and role of the glial cells in variously modulating the activity of the nervous system – especially the CNS –, I sketch an ideal system formed by two structures that result functionally interconnected. On a first level, there is a wired network the operation of which should resemble that of a neural network, while on a second level an autonomous network – with structural and functional features similar to the ones of the presynaptic glial cells of the CNS – spreads over the former and, in determinate conditions, leads its functioning according to a global systemic need for internal activation equilibrium that can be somehow assimilated to homeostasis. So, what I want to highlight, although in a very simplified way for now, is that these networks cooperate with different roles and mechanisms in the constant pursuit of the integrity of the system as a whole and that, over the time, they are mutually subject to structural enhancements and functional reinforcements making them evolutionary entities in all respects.

My purpose is hence to outline the basic functioning of an ideal system that reacts to external and internal stimuli affecting it by activating its response networks in such a way that the activation state of the latter within certain physiological parameters (equilibrium state or cenesthesia) denotes the free-disturbance condition that can be pursued and achieved exactly through more or less complex activation patterns and the final effects resulting from them. In my perspective, such a system should formally represent what neurons and glial cells do – each according to their own functional properties – whenever some environmental or internal disturbance affects it by triggering a first reaction in terms of network activation beyond a certain equilibrium level and thus forcing it to organize responses, within the networks themselves, to return to an equilibrium state.

1. Introduction

Since, in order to grasp the criteria according to which the ideal system sketched here works, it is preliminarily helpful to determine how glial cells could interact with neurons in the physiology of the real nervous system, let us first see briefly and summarily what is to date known about glia and some of their specific properties that could in fact give them a significant role in managing and implementing higher neurological dynamics such as decision-making processes and other non-automatic response processes. For this purpose, we can consider the following morphological, physiological and functional features revealed over the past few decades¹.

I) Glia transmit information by means of *calcium waves* (Ca^{2+}); this ion is released inside the cells as the result of appropriate external chemical stimulations on specific receptors, and thanks to the work of internal second messengers, or conveyed from cell to

cell through *gap junction* connections.

II) Glia communicate with neurons in various ways, both at the synaptic level and more generally at the structural level. This communication occurs mostly using the same transmitters used by neurons to communicate each other.

III) Glia have a *modulatory* power on the neural activity which they exert both at the synaptic level and at the network level, thus contributing in various ways to regulate the global functioning of neural transmission.

IV) Glia, specifically astrocytes, can communicate with many neurons even located distally from each other, thus constituting a sort of glial-neural *hyper connection* that adds to the one structured on the wiring of the neurons themselves.

V) The Ca^{2+} flow can travel in both directions within the cell. This is to say that, unlike what occurs within the neurons where the ionic flow only follows the body-terminal direction, glia have the

advantage of being able to communicate *in tandem* with each other. VI) Astrocytes exhibit a certain phenotypic variety that is most likely correlated to a functional ductility about which, however, little is known at present.

VII) Thanks to these (and other) properties, astrocytes seem to be in the condition to constitute a real *ubiquitous* communication network and, through it, to detect and control nervous processes occurring even distally from each other according to a unitary systemic operation.

The idea is that these general and fundamental properties, acquired by evolution, give glia the ability to develop a ubiquitous (wide-ranging) internal communication network and, thanks to it, to variously control neuronal activity in compliance with global systemic requests the satisfaction of which is imposed on the several districts active in a given temporal context in order to adequately respond to stimuli or disturbances and regain a state of equilibrium.

2. N-G System

The *N-G System* described below is a purely ideal and formally defined system that should somehow reproduce what occurs inside the CNS, in response to perturbing stimuli of various origins, by virtue of a coordinated work of neurons and glia, each according to their specific functional competences.

The N-G System is formed by:

i) a *wired* network $N = [N \rightarrow]$, in which each connection $n \rightarrow m$ between two elements of N is: (a) *unidirectional*²; (b) *excitatory* (+) or *inhibitory* (-) in output with respect to the element m reached by \rightarrow and (c) subjected to *potentiation* and *weakening* depending on its use and

ii) a network $G = [G \leftrightarrow]$, in which: (a) each connection $g \leftrightarrow g$ between two elements of G is *bidirectional*; (b) each g is *structurally* and *functionally linked* to multiple elements n by means of \rightarrow ; (c) each g can be activated by \rightarrow and it can in turn exert a modulatory effect on \rightarrow that can be either *exciting* or *inhibiting* in accordance with the operational requests of the context; (d) G is divided into groups of g interconnected by \leftrightarrow (denoted by G^*) that form *ubiquitous* communication networks spread across the $n \rightarrow$ connections to which their components g are structurally and functionally linked and (e) each G^* can be subjected to structural extensions depending on the effective dynamics occurring over the time between the g and n structurally connected and functionally interacting³.

The fine structure of the N-network is then established through the following definitions.

[Def. 1]

Let us define *line* in N a structure L such that:

- i) if n and m are elements of N then $L = n \rightarrow m$ is a line in N ;
- ii) if L_1 and L_2 are lines in N then $L = L_1 \rightarrow L_2$ is a line in N ;
- iii) if L_1, \dots, L_n are lines in N then $L = L_1 \rightarrow L_n \& L_2 \rightarrow L_n \& \dots \& L_{n-1} \rightarrow L_n$ is a line in N ;
- iv) if L_1 and L_2 are lines in N then $L = L_1 \rightarrow L_2 \& L_2 \rightarrow L_1$ is a line in N – i.e. a line can be formed by lines reciprocally connected;
- v) nothing else is a line in N .

[Def. 2]

Given two lines L and L' in N , let us define L' *convergent on* L – shortly $L' \text{-}_{conv} L$ – when:

- i) $L' \rightarrow L$ (in this case L' is said *immediately convergent on* L) or
- ii) for some $L^\circ \text{conv} L, L' \rightarrow L^\circ$.

Given a line L , let us define *convergence point* of L – shortly $\text{conv} L$ – the line L^* in L such that, for every line L' in L , L^* is not convergent on L' . Intuitively, L^* represents the final result of the entire wiring of L .

[Def. 3]

Every line L has an activation level that can vary from 0 to a maximum⁴. Symbolically expressed as:

$$0 \leq_{act} L \leq \max.$$

Such a value depends on the global activation state of N at a given time t_x . Thus we can put $_{act} L_{tx}$ as *the activation level of* L *at the time* t_x .

[Def. 4]

Given L and L' such that $L' \rightarrow L$ and given $_{act} L_{tx}$, let us put $_{act^*} L'_{act} L_{tx}$ as the *minimum activation level that* L' *must have to change the activation level of* L *at the time* t_x .

[Corollary to Def. 4]

In general, if $L' \text{conv} L$, the symbolic expression $_{act^*} L'_{act} L_{tx}$ denotes the minimum activation level that L' must have to change the activation level of L at the time t_x .

Based on what has been just defined, we can go on and say that the N-G System basically works with the aim of maintaining a state of activation internal to N in which every line L in N :

- i) discharges its activation out of L itself or
- ii) exhausts the amount of activation within itself;
- iii) a *stagnation tolerance value* stag^* inside L is admitted.

Such a condition is called here *coenaesthesia* and it has to be spontaneously reached within a determinate time before the system enters a state of *disorder* to overcome which it must elaborate appropriate and more or less complex reactive responses. This is to say that N-G does not admit any prolonged and localized stagnation of activation, above a given tolerance value. I.e., for every L :

$$\text{stag} L \leq \text{stag}^*.$$

We have to emphasize that *stagnation* does not equate to *prolonged activation flow* in L . The latter represents the dynamics in which the several $L' \text{conv} L$ rhythmically acquire and discharge or exhaust activation, which does not cause any overall disorder in the N-G system. A stagnation in L occurs when, for some reason, there is no activation turnover and this condition can essentially take three different forms:

- 1) an activation conflict between two lines immediately convergent

on *convL*; which can occur when these two lines are both excitatory on *convL* but reciprocally inhibiting and they have the same activation level;

- 2) a persistent activation on *convL* which however turns out to be too weak to find a discharge or exhaustion through the latter and
- 3) an amount of incoming activation that exceeds the discharge or exhaustion capabilities of the *convL*.

When a line *L* fails to discharge or exhaust within a certain time, and thus enters a state of disorder at a certain time t_x (symbolically denoted by DLt_x), the N-G system responds by triggering dynamics of reorganization of the global activation framework inside its structure N in order to regain *k* (coenaesthesia) and it does this involving not only the level of neural processing but, if it comes out to be necessary, also the glial one, each according to different operating times.

The first step to overcome the disorder state is a competence of N itself. This is because, in the real model provided by the animal CNS, being the *neural* information processing and transmission times much faster than the glial ones, it is physiologically normal for neurons to react first. So, faced to a DN^6 , N starts to seek some solution consisting in a rearrangement of the global activation lines that is able to unlock the activation impasse occurring in *L* through a feedback path having a final discharging or exhausting effect on *L* itself. By virtue of its rather rigid wiring, N can act in a one-way direction only starting by *L* and following the connection pathways signed by \rightarrow . This structurally constrained *modus operandi* inevitably imposes that N only searches paths being somehow already marked inside the wiring \rightarrow , although not yet factually used, and strictly centripetal from *L*. It means that a reaction to DL led by N can only be aimed at finding solution strategies arising from the involvement of *centered on L* \rightarrow -paths that result to be more or less use-strengthened at the time of processing. Thus, in psychological classification, a response pursued in this way could be included in *instinct*, *automatism* or in some form of response processing immediately deriving from these. In this dimension, there seems to be very little room for a search for responses that are somehow *creative* and potentially alternative to each other. The N-processing – similar to neural one – works in a rather rigid or stereotyped way and can thus only slightly extend the repertoire of possible responses in the ongoing context. As in action-oriented decision-making or pure speculative thinking, the N-G system also requires a greater procedural flexibility to obtain a wider range of possible responses to its inner problems – what is identified here as *L*-line activation disorder.

3. Principle Of N-Dominance (Over G)

Before seeing when and how the G component comes into play to deal with a DL, we need to make explicit a hierarchy existing within the N-G system⁷.

N exerts a functional dominance over G and this dominance occurs as:

- 1) a faster processing speed: each activation in N precedes and triggers a related activation in G – each *n* is functionally related to an *g* and each *g* can be related to more than one n^8 –;

- 2) temporally prioritized approach of N to disorder states within itself;

3) dependence of any modulatory activity of G on N on any other autonomous activation state occurring in N that affects the former. The third constrain simply expresses the inner dynamics according to which G can modulate N-activities being somehow already started and defined but it cannot determine anything in N *motu proprio*. This is why any autonomous or independent N activity can interrupt or modify an ongoing G-modulatory activity at any time of processing, forcing G to reorganize its functional responses.

Therefore, as said above, the system N-G primarily reacts to a disorder state in a line *L* in N at the time t_x – i.e. a state in which $stagL > stag^*$ – tackling the problem in N itself, according to the processing mechanisms conditioned by the wiring of N and in N-times being much faster than the ones of G. Shortly and symbolically:

$DLt_x \Rightarrow$ N-reaction in NT (with NT just denoting *N-times*)

However, as soon as N is activated to react to DL, the *g*-components of *G* structurally and functionally linked to the *n*-components of N forming $convL^9$ are also activated and their activations follow the evolution of the N-processing that searches for a solution to DL. If, after a certain amount of time, N is not able to find a solution, entering into a sort of impasse, and if this time is enough for G to trigger its own internal communication¹⁰, then the latter comes into play and, through a significantly different procedure strategy, faces the problem. Starting from the DL with respect to which N failed, a specific *G*L* network begins its task. Shortly and symbolically:

$DLt_{x+NT=GT}$ *N-failure* \Rightarrow *G*L* (with $_G T$ denoting *G-times*)

What *G*L* exactly is and how it functions just represent the core of the ideal N-G system described here. In this regard, it has to be firstly emphasized the supporting structure of *G*L* consists of. So, we can say that *G*L* is a *g*-network formed by:

- i) the set of $g \subset G$ that are structurally and functionally linked to the $n \rightarrow$ connections *basically* forming *L* in all its convergences and
- ii) the set of $g \subset G$ that are structurally connected – by means of \leftrightarrow – to the *basic* *g*-units of *G*L*¹¹ and that can *actually, at the time* $DLt_{x+NT=GT}$ communicate with them¹².

Point ii) establishes something that is crucial for the structural and functional nature of a *G*L* network. It expresses the temporally determined limitation of *G*L* – which can however receive extension and enhancement through its actual use, as we will see shortly. More specifically, point ii) says that, at the time when DL occurs and the G-processing comes into play, the basic *g*-units – i.e. the *g*-units linked to the N-center from which *G*L* develops – are able to effectively communicate with only a part of the *g*-units in *G* with which are structurally connected. They, as their ideal glial counterparts, begin their *functional life* with a fundamentally

defined endowment (genotypic heritage), but it is then through practice that the potential can be more or less and in somewhat different forms actualized (phenotypic expression).

Thus, if this is the basic architecture of a G*L network, we have now to see how it works once it starts its task temporally and in the merit consequent to that carried out by N without success. In this regard, we can first say that G, just like N, does not tolerate any prolonged and stagnant activation states within itself. It spontaneously looks for its coenaesthesia and a DL inevitably causes stagnation of activation in the g linked to the $n \rightarrow$ composing L, that is, it causes a departure from coenaesthesia in a certain area of G. A G*L network therefore has the precise task of seeking to break the deadlock in N in order to regain its own inner equilibrium and to do so by the tools that G is equipped with.

Let us now see according to which procedural mechanisms a G*L network acts, reiterating that it comes into operation exactly starting from a precise DL left by N without any satisfactory coenaesthesia solution, that is, from a DL in which the L to be considered can also be an unsuccessful reworking of a first problematic L'. Anyhow, in compliance with the principle of N-dominance, G*L takes control of the process starting from:

$$DL_{x+NT=GT}$$

Imagining how real glial cells (specifically astrocytes) might actually behave in such a dynamic – based on what is known to date about their physiological characteristic and functional properties¹³ – we can describe the progression of the work a G*L network by dividing it into several phases, each with particular implementation modes and determined aims. What is now being explained refers, for the sake of simplicity, to a single ideal focus L of activation disorder, but the discussion could obviously also be extended to a condition in which there are multiple foci of activation disorder existing simultaneously in the N-G system.

Phase I

In the first phase, the G*L network carries out a work of selection among several possible intervention directions, in order to then operate in a targeted manner in attempt to resolve the activation disorder contained in L. This phase is in turn divided into several procedural steps.

Step 1 – As first step, the G*L network has to *search* the several pathways $n_1 \rightarrow n_2 \rightarrow \dots$ which can be identified by the g-units being actually communicating – through \leftrightarrow – with the coordination center constituted by the g-units linked to the $n \rightarrow$ in L^{14} . The number and length of the pathways $n \rightarrow \dots$ just identified depends precisely on the current extent of communication within G*L and originating from the L-linked g-units.

Step 2 – In the first step G*L defines the *map* of all the pathways $n \rightarrow \dots$ that can be reached by the $g \leftrightarrow$ -network centered on L and its current extension in communication capacity. The second step of the G*L process is to identify the lines $L_1 \dots L_n$ that:

- i) can be formed starting from the $n \rightarrow \dots$ -map previously defined and
- ii) can have some *feedback* on L, i.e. can somehow modify the activation state of L.

This is to say that G*L seeks the *inherent-map* lines that could provide some effect on L in case of activation.

Step 3 – The third step requires that the structure G in general – and thus even a G*L network in particular – owns the specific property to distinguish for every basic connection $n \rightarrow m$ in N whether it is *excitatory* (+) or *inhibitory* (-), i.e. whether it tends to activate or to negatively modulate what comes next within the same pathway¹⁵ \rightarrow^{15} . By virtue of this capacity, G*L makes a selection of the L_x identified in the previous step. Specifically, it has to select only the L_x such that:

$$DL_x \leq DL$$

i.e. it has to give up, within the limits of its tools and according to its current communication power, any potential feedback that can increase the ongoing disorder condition. This selection can be done just following the \rightarrow -wiring that forms the L_x and assessing the possible global effect of the single \leftrightarrow -connections present in it in light of the general activation state of N in which the whole G also is involved due to its close structural and functional relationship¹⁶. The processing criterion underlying this operation is trivially to avoid, in the phase of active intervention of G*L on N – that we will see later –, favoring lines that would worsen the situation rather than alleviate¹⁷.

Step 4 – The fourth step is *strategically* tied to the third one and its implementation requires a further faculty with which G is provided – again in analogy with its biological counterpart represented by astrocytic cells –. It is hence imagined that the g-components of G, each of which is linked to more than one $n \rightarrow m$ connection of N, are equipped with the capacity to detect and register the strength of the $n \rightarrow m$ activation transmission, i.e. the ease with which the activation flow passes from n to m ¹⁸. This property is used by G*L to perform an additional selection on the lines L_x chosen in compliance with the criterion described just above. In fact, the several L_x selected in that way do not cause more disorder if assessed independently of each other. However, it can occur that two or more lines cause an increase in disorder if simultaneously considered or that the one negatively interferes with the other, that is:

$$DL_x \& L_y \& \dots > DL \text{ or } L_{x \text{ act}} \& L_{y \text{ act}} \& \dots < L_{x \text{ act}} \text{ aut } L_{y \text{ act}} \text{ aut }^{19} \dots$$

Such a danger has thus to be averted. To this end, G*L has to select among the lines that, if activated together, would cause disorder or would reciprocally interfere and give priority to that or those that appear to be *stronger*, i.e. easier to bring to a state of activation sufficient to have some effect on L²⁰. If two or more lines to be selected according to the criterion of *strength in connections* come

out to be equally strong then G*L can resort to a *random choice*, without thereby modifying anything, as far as it can be established in this phase of mapping and preliminary selection.

The first phase, that ends with the identification of a certain number of lines $L_1 \dots L_n$ having determined characteristics, gives then way to a second phase in which the G*L network assumes an active role on N.

Phase II

In this second phase of the G*L's work, G's claimed property to modulate the \rightarrow -connections in N, both positively and negatively, comes into play²¹. The aim of G*L is to:

i) induce the lines $L_1 \dots L_n$ previously chosen to switch from $L_x <_{act^*}$ to $L_x \geq_{act^*}$, i.e. lead the various L_x lines until an activation state such that they can change²² the activation state of L through some feedback and

ii) keep any line L' identified as *potentially disordering* or *disturbing*, according to a previous selection, in an activation state $L' <_{act^*}$ ²³.

The first task consists of a *positive modulation*²⁴ on the \rightarrow -connections in L_x in order to increase its activation level, while the second and parallel work is configured as a *negative modulation*²⁵ exerted on the \rightarrow -connections that do not belong to any L_x and that contribute to forming some L' given up as potentially disordering or disturbing

The G*L modulation process, just because it is defined on the basis of what glial cells could do in the CNS, needs to be clarified in more detail.

First of all, by virtue of the principle of N-dominance, what G*L does can at any moment be *subverted* by what independently of G*L – in a spontaneous way or induced by external factors – occurs within the activation dynamics affecting N. This means that both the positive modulations and the negative ones could be interrupted at every time of the G*L-processes if the activation framework in N network changes in such a way as to make the operations performed by G to solve an activation disorder problem in L no longer relevant due to modified needs of the system itself centered on N. G, with its local G*.. networks, always chases the events in N and starts each time from what N leaves unsolved.

A second point to be highlighted is that G*L is not able to generate an immediate activation on the \rightarrow -connections just as is not able to produce a deactivation²⁶. Therefore, G*L positively modulates each \rightarrow -connection forming a line L_x so that N itself finally reaches an activation level sufficient to provide feedback on L. In parallel, G*L negatively modulates all the \rightarrow -connections extraneous to each L_x and converging on some potentially disturbing L' so that they remain at an activation level not sufficient to modify what occurs in L_x by the positive work of G*L itself, but it cannot block a possible activation exploit arising autonomously from N.

Furthermore, and very importantly, a G* network is *functionally*

limited, that is – as said above – it has an actual communication range that only partially covers the potentially available \leftrightarrow -connection structure in which it is inserted²⁷. For this reason, the mapping through which G*L identifies the lines $L_1 \dots L_n$ to be supported reaches as far as the g-units centered on L can actually communicate. It follows from this premise that any L_x could in turn be convergent on some other L° – i.e. $L_{x-conv} L^\circ$ – not identified by G*L at the time of processing and such that, once activated thanks to the G*L modulation, it gives feedback also unexpected by G*L mapping – i.e. L° originates effects that escape the selection process of G*L due to the current limitations of communication among g-units –.

Well, pointed up these essential details, we have enough items about the matter to see what specific results the integrated processes of *mapping-selection* and *modulation* carried out by the G*L network can produce. Remembering that a G*L modulation is a slow job that tends to stimulate N to eventually and definitively trigger the activation of the L_x previously chosen, we can imagine that such a job exactly starts from the sources \rightarrow ²⁸ of every L_x – and then continues along the directions imposed by the \rightarrow -wiring of L_x – as soon as the selection of all the acceptable lines is concluded according to the criteria of *completeness* and *caution* seen before²⁹ and we can also imagine that the several L_x get activation at different times depending their structural complexity and internal connection strength. However, once L_x is activated, it can happen that L_x converges on some other L° – i.e. $L_{x-conv} L^\circ$ – and so does every other L_y by determining a new and possibly unexpected³⁰ global activation framework in N – that we can symbolically put as G*N –. This possibility makes the final pattern achieved by a G*L-mapping-modulation cycle the following:

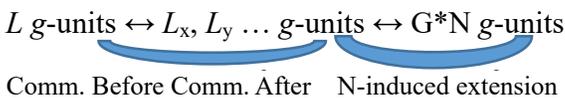
$$L_x \& L_y \& \dots G^*N.$$

It is to be pointed out that a G*N can be achieved by a single line or by multiple lines. This depends on the times need by G*L modulation to bring the various lines to an activation level $act \geq_{act^*}$. If the times are such as to trigger N-responses in parallel then two or more lines can originate a single G*N. In any case, the end of a G*L mapping-modulation cycle, barring independent and alternative N-activities occurring during the G*L processing time³¹, comes when some G*N is triggered at a sufficient N-activation level, thus falling again within the exclusive competence of the N-processing with its T_N execution time. A G*N can then essentially present three distinct and alternative outcomes in terms of the general activation state resulting in N and including a new activation state just for L ³², namely:

- stagG*N \leq stag*;
- stagL > stagG*N > stag* or
- stagG*N \geq stagL > stag*.

Keeping in mind that processing is now back under the control of N, we can think of G as entering a standby state waiting for exactly what N can decide. In the first case, in accordance with the principle of regained coenaesthesia, N will tend to exhaust any targeted reactive process and, for the same reason, G will also cease its own

activity. Instead, in the second and third cases, N will be forced to continue the search for an internal reorganization to overcome the activation impasse still in place, although with different pressure in the two respective contexts. So, both in the case b) and in the case c) N takes control of the situation but does so starting from a different framework compared to the temporally previous one represented by DL. A different framework for two reason. First, the origin of the coenaesthesia disorder is now somewhere in G*N and no longer or no longer necessarily centered right and only on L. Furthermore, and most importantly, both the N-wiring and G-connection network have undergone modifications due just to the N-G*L processing cycle recently concluded. The lines $L_1 \dots L_n$ positively modulated by G*L, regardless of whether they have reached full activation or not, have anyway been reinforced, through use, in their \rightarrow -connections and are therefore now more identifiable, exploitable and avoidable – depending on contextual convenience – by N itself that hence obtains a functional improvement from its systemic counterpart G. On the other hand, any possible further activation produced by N and going beyond the functional limits of G*L – i.e. an event like the one represented here as G*N – brings with it a parallel activation of the g-units linked to the \rightarrow -connections affected by the process. This in turn determines an expansion of the effectively available communication network among g-units that were previously only structurally connected by \leftrightarrow . As if N, through G*N, acted as a radio bridge between the g-units of G*L and those linked to G*N. Schematically:



But that's not all. The very use of communication among g-units in G*L makes the communication itself stronger, in the sense that the information, conveyed through the \leftrightarrow -connections, can flow more easily and therefore, with the same amount of activation, the message can reach further and spread with a wider radius through the pathways defined by \leftrightarrow . In this way g-units, that were not reachable from other g-units before a certain practical work, subsequently become reciprocally accessible precisely thanks to the functional reinforcement deriving from use³³. As we can notice, the G structure in its whole gets a functional enrichment from two sources and both coming from the activity of its G*.. networks: on the one hand, G is *passively* improved by the extension G*N occurring in N and promoted by the G*.., on the other hand, as just highlighted, an autonomous strengthening originates from the actual activity of any G*.. itself in performing its own coenaesthesia task. So, in case of a second G cycle starting from G*N at the time $t_x + T_N = T_G$ – i.e. a cycle denoted as $G^*(G^*N)t_{x+TN=TG}$ –, G*(G*N) network will be in the condition to count on a wider and hence functionally better potential of effective communication among g-units.

Each coenaesthesia cycle in the N-G system of the N-G*.. –N type determines a mutually stimulated evolution in the two subsystems N and G that forms it.

4. Final Remarks

To conclude we can simply reiterate what the N-G system wants to be and try to show what utility it could have. First of all, the structure of N-G is ideally and roughly derived from what is hypothesized to be a possible functional interaction between the glial cells and neurons in the CNS aimed at seeking and implementing non-automatic responses to events that affect the system itself in a somewhat unbalancing way. We say possible interaction because little is still known about the conjugated systemic behavior of glia and neurons. To date many scientific clues suggest that such a functional synergy exists, however much still needs to be investigated to confirm this reasonable suggestion. Thus, within a so defined framework, the N-G system is conceived as a theoretical and oversimplified model in which a idealized neural-glial cooperation works in order to preserve or regain a state of dynamic equilibrium inside both components and thus inside the system in its whole. This is to say that N and G are thought as interdependent agents in pursuing their coenaesthesia goal. The model offered here is not intended to represent any specific reactive dynamics that can occur in a biological organism grappling with the problem of finding adequate responses to overcome a somehow disturbing condition. More generally, the N-G system aims at providing a formal image of the mechanisms that might underlie higher processes such as problem solving, decision making or abstract thinking. Of course, without any claim to representative exhaustiveness. What would be desirable is that such a model could be helpful, in a heuristic perspective, for designing targeted research both in the field of neurobiological sciences and in that of artificial neural-(glial)-inspired systems. For my part, my next goal is to outline a mathematical, and therefore procedurally precise, formulation of the functioning of a G*.. network, as it has been conceived here in its active dependence – if I may exploit this oxymoron – with respect to what occurs in N [1-95].

Declarations

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Notes

¹At the end of the text, some essential references concerning the main findings on the issue are provided.

²That is, the command transmission may only occur in one direction.

³The exact meaning of these definitions will become clearer shortly.

⁴It is not relevant here to specify the way in which the activation level can be established. For our scope, it is enough to know that such a level is not unique but can vary on a limited continuum of values from non-activation to maximum activation.

⁵stagL just denotes the amount of stagnant activation in the line L that must always be lower than stag* representing the value of stagnation tolerated by the system – to be acceptable.

⁶A disorder state in some line L in the sense specified above.

⁷Even in this respect, the reference is the organization of the neural-glia biological system.

⁸According to the structure of the tripartite synapsis.

⁹The convergence point of a line L is exactly the point in which activation discharge or exhaustion either occur or cause disorder DL.

¹⁰The G-times are slower than the N-ones.

1 In the sense specified at point i).

2 The symbol \leftrightarrow denotes the connection type characterizing G. that in the biological glial system should correspond to the gap-junction connection network thanks to which astrocytes communicate with each other through Ca²⁺ waves of varying frequency and amplitude.

¹³I repeat once again that the system presented here is intended to be an ideal and simplified model of how the neural-glia system could really work in shaping complex and non-automatic responses to events that are somehow problematic for the integrity and equilibrium of the system itself. Of course, this is only a hypothetical construction based on what is known about the functional interaction between glial cells and neurons and therefore more than one crucial point of this theoretical system should be carefully investigated on an experimental level. My hope is that an ideal model like this can at least serve as a heuristic indication of how and where one can then empirically and in appropriate contexts further research in order to better understand whether the glial cells are really able to actively and with a significant role intervene in the onset of higher-order nervous processes.

⁴We have to remember that \leftrightarrow establishes connections among g but the actual communication ability depends on the use and it is subjected to both autonomous and \rightarrow -correlated enhancement and extension.

⁵Such a property recalls the glial one – not yet tested but reasonably hypothesized – of functionally reacting in a different way depending on whether excitatory rather than inhibitory neurotransmitters are present in the shared synapses.

⁶The idea, derived from the prerogatives of astrocytes in CNS, is that G, thanks to its faculty to ubiquitously map the N network and the activation foci in it as well as to communicate information within itself in both centrifugal and centripetal direction from any point, is able to perform a real tomography of the states in which N or parts of it are found.

⁷This selection criterion could be defined as minimal risk in changing.

⁸In this case too, the reference is given by what is reasonably hypothesized about the functional properties of perisynaptic glia. Indeed, it is highly plausible that astrocytes can assess how easily a presynaptic terminal triggers an action potential in the postsynaptic target and consequently set their functional behaviour according to the contextual necessity.

⁹Aut denotes the exclusive disjunction.

²⁰Even this criterion of economy recalls what emerges in the biological systems where the organization of responses is normally aimed at the least possible expenditure of energy to achieve the goal.

²¹Again, this property of G is derived from what is known about the actual capacity of some glial cells to influence and modify in some way the neural activation dynamics.

²²A change in the desired way.

²³G*L builds a sort of Faraday Cage around the Lx.

²⁴What corresponds to an excitatory effect in neuronal terms.

²⁵What corresponds to an inhibitory effect in neuronal terms.

²⁶Even for this functional limit, the archetype is the interaction between glia and neurons in the NS. The former can in fact act at most with an agonistic or, vice versa, antagonistic role on the synapses. However, they cannot generate an action potential by themselves nor determine an inhibition. They can just favour one or the other process so that neurons can then definitively complete it.

²⁷A time-bound limit that can be reduced through use.

²⁸That is, from the most elementary components of Lx identified by G*L.

²⁹As said, G*L pushes its search in depth by following the $n \rightarrow$ connections as far as its g-units are able to communicate with each another and thus investigate what is relevant to a good choice. The lines Lx identified in this way are therefore the most articulated and reciprocally checked possible within the communication limits of G*L at the processing moment

³⁰Possibly unexpected because it can also happen that nothing substantially different is triggered by the activation of Lx.

³¹Always for the principle of N-dominance.

³²The G*L processing is structured in such a way as to provide feedback on the activation state of L.

³³Even this evolutionary property attributed to the G structure is thought to be representative of what appears to belong to glial cells in the nervous system. In fact, just like neurons, glia – astrocytes at least – also seem to own the prerogative of improving their functional

performances depending on the practice as such and on the specific type of activity they are called to carry out, support or assist. Therefore, like the neuronal system functionally improves itself both by making synaptic transmission easier and by broadening and enriching its own circuit architecture, glia also functionally strengthen themselves by increasing the communication power within their gap-junctions-network, that is, by making the flow of calcium ions gradually less subject to structural constraints and freer to spread centrifugally from any internal source of emission.

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